## AMENDMENTS TO THE CLAIMS:

This listing of claims will replace all prior versions, and listings, of claims in this application.

1. (Currently Amended) A method to correct a phase of a received phase modulated (PM) signal, comprising:

applying a received phase modulated (PM) signal to a first circuit branch and a second circuit branch;

in the first circuit branch, selecting k data bits from the received PM signal, wherein a data bit received most recently corresponds to time  $t_1$  and wherein k is an integer greater than  $t_1$ ;

determining a phase error based on the k data bits;

in the second circuit branch, delaying the <u>received PM</u> signal to a second time  $t_2$  that is later than  $t_1$ ;

applying the phase error to at least a portion of the delayed PM signal at the second time t<sub>2</sub>;

calculating a phase offset from based on the delayed PM signal; and using the phase offset to correct the phase of a PM signal received at a time later than  $t_1$ .

- 2. (Original) The method of claim 1 wherein selecting k data bits comprises arranging the k data bits serially so as to alternate between in-phase and quadrature bits.
- 3. (Original) The method of claim 1 further comprising:

setting k equal to a total number of data bits that influence the phase of the received PM signal at the first time  $t_1$ .

- 4. (Currently Amended) The method of claim 1 wherein  $k=1+\frac{1}{BT}$ , wherein B is a bandwidth of the received <u>PM</u> signal and T is a bit interval of the received <u>PM</u> signal.
- 5. (Currently Amended) The method of claim 1 wherein determining a—the phase error includes accessing, using the k data bits, a lookup table.

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- 6. (Currently Amended) The method of claim 5 wherein determining a—the phase error further comprises inverting an output of the lookup table when the most recent data bit is one of an in-phase or a quadrature data bit.
- 7. (Currently Amended) The method of claim 1 wherein determining a-the phase error based on the k data bits comprises correlating the k data bits except the most recent data bit with a derivative with respect to phase of a conjugate of a reconstructed waveform.
- 8. (Currently Amended) The method of claim 7 wherein the derivative with respect to the phase is stored in a lookup table.
- 9. (Original) A circuit to correct a phase of a phase modulated (PM) signal, comprising:
- a first circuit branch wherein a primary phase shifter, a register, one of an algorithm sub-circuit and a lookup table sub-circuit, and a loop phase shifter are arranged in electrical series, in that order;
- a second circuit branch having an input in parallel with the first circuit branch, wherein a delay block and the loop phase shifter are arranged in electrical series, in that order;

the register for storing at least two data bits sampled from the PM signal; and the loop phase shifter having an output coupled to an input of the primary phase shifter.

- 10. (Original) The circuit of claim 9 wherein the at least two data bits comprises a series that alternates between an in-phase bit and a quadrature bit.
- 11. (Currently Amended) The circuit of claim 10 wherein the first circuit branch further comprises a complimentor complement block disposed between the loop phase shifter and the one of an-the algorithm sub-circuit and a-the lookup table sub-circuit.

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- 12. (Currently Amended) The circuit of claim 9 wherein the at least two data bits comprises  $k=n(1+\frac{1}{BT})$  data bits, wherein n is a number of samples per bit interval that is greater than or equal to one, B is a bandwidth of the received PM signal and T is a bit interval of the received PM signal.
- 13. (Currently Amended) The circuit of claim 9 wherein the one of the algorithm sub-circuit and the lookup table sub-circuit produces the phase correction by correlating all data bits in the register, except the most recent data bit, with a derivative with respect to phase of a conjugate of a waveform reconstructed from the received-PM signal.